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**AUTOMOTIVE  
CONFERENCE 2023**  
Europe

# How to achieve full coverage of configurable code through dynamic testing and static analysis with Polyspace

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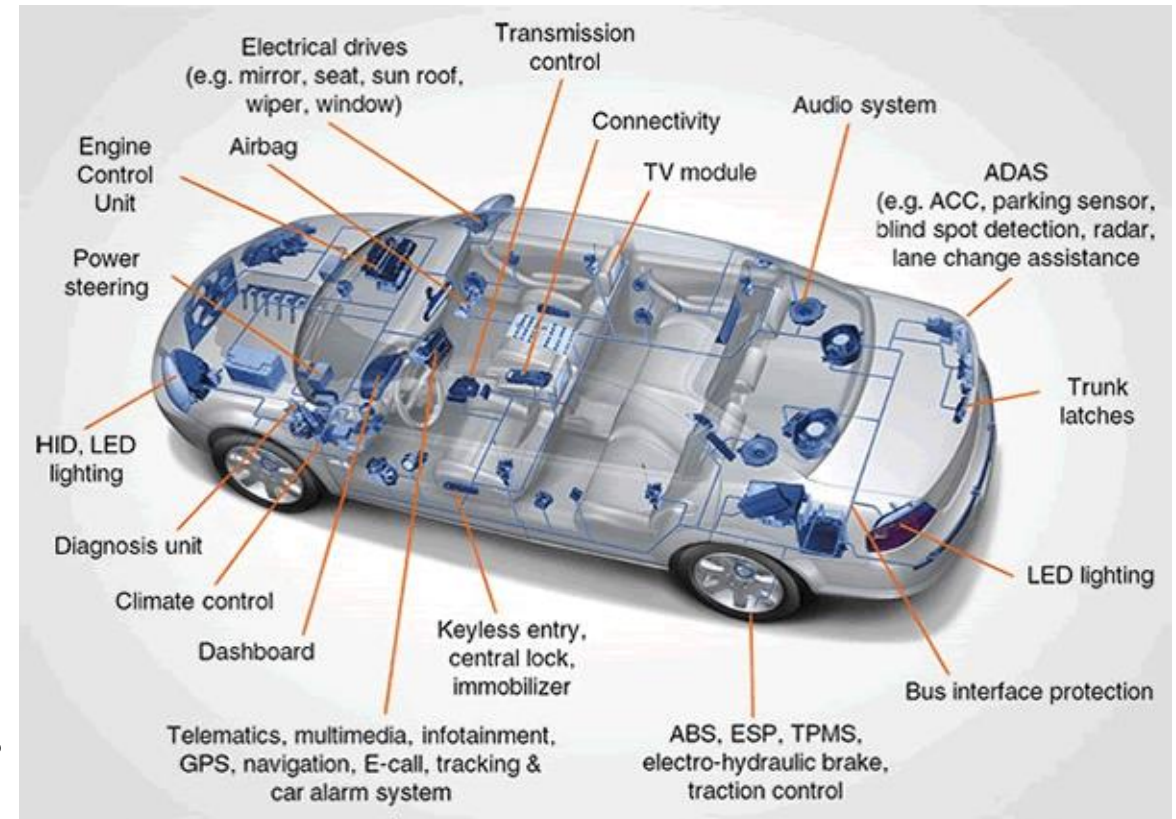


# Agenda

- Automotive connectivity evolves
- Certification is key to deliver safe and robust Software-defined vehicles
- STMicroelectronics AUTOSAR software products
- STMicroelectronics methodology
- Verification and Validation process
- Leverage Polyspace to analyze Software variants

# Automotive connectivity evolves

- Electronic systems are a fundamental part of any automotive environment
- Electronic control units (ECU) to control sophisticated engine functions:
  - Anti-lock braking systems, traction control systems, park assistance systems, etc..
- Internet of Things (IoT) exposes ECUs to hacker attacks:
  - We are connected to the vehicles using Cellular, Wi-Fi, Bluetooth, etc..
- Complex ECU system caused increase of embedded software and networking in vehicles





# Certification is key to deliver safe and robust Software-defined vehicles

- ISO 26262 for functional safety
- ISO/SAE 21434 for cyber security
- Static Analysis evaluation is fundamental to ensure
  - Software quality
  - Compliance with regulations
  - Ensure that code follows coding standards as MISRA, Cert-C and CWE
- STMicroelectronics relies on Polyspace to fulfill ISO 26262 and ISO/SAE 21434 standard requirements



# STMicroelectronics AUTOSAR software products: development challenges

- STMicroelectronics develops AUTOSAR MCAL drivers for Automotive customers.
- Use of AUTOSAR system architecture reduce development cost and avoid re-development of SW for similar application
- Drivers are developed for PowerPC and ARM architecture and are configurable for each customer
- High level of driver configuration leads to a **huge number of software variants**

Driver	Number of Boolean preprocessor macro (#define)	Number of SW variants considering only Boolean parameters
MCU	58	$2^{58} = 288 \cdot 10^{15}$
CAN	50	$2^{50} = 112 \cdot 10^{13}$

- Fulfill Automotive **safety and security standards**

## Methodology to verify MCAL driver variants

- The AUTOSAR software team defined a methodology to select the minimal subset of variants to obtain the full structural coverage of the configurable code
- Variant selection
  - Human and iterative process based on developer expertise
- Measure completeness of variants subset
  - Metrics: Statement Coverage, Decision Coverage, MC/DC
  - Aggregate code coverage: an internal developed tool aggregates the coverage results for each software variant generating a report containing the aggregated coverage score and map.

# Aggregated code coverage

- Aggregate results ensure goodness of variant set

Aggregate

Reachable lines = 11 - Tested Line = 8  
Statement coverage score = 72%

Variant  
MCU\_DEV\_ERROR\_DETECT=STD\_ON  
MCU\_INIT\_VALID\_POINTER\_REQUIRED= STD\_ON  
  
Reachable lines = 10 - Tested Line = 7  
Statement coverage score = 70%

```

FUNC (void, MCU_CODE) Mcu_Init (P2CONST (Mcu_ConfigType, AUTOMATIC, MCU_APP
{
    Mcu_CfgPtr = NULL_PTR;

    /* @implements DMCU06100 */
    #if (MCU_DEV_ERROR_DETECT == STD_ON)
    #if (MCU_INIT_VALID_POINTER_REQUIRED == STD_ON)
    if (NULL_PTR == ConfigPtr)
    #else /*MCU_INIT_VALID_POINTER_REQUIRED == STD_ON*/
    #if (NULL_PTR != ConfigPtr)
    #endif /*MCU_INIT_VALID_POINTER_REQUIRED == STD_ON*/
    {
        /* polyspace +2 MISRA-C3:17.7 [Justified:Unset] "Det APIs r
        Det_ReportError ( (uint16) MCU_MODULE_ID, (uint8) MCU_INSTA
        (uint8) MCU_INIT_ID, (uint8) MCU_E_INIT_FAILED);
    }
    else
    {
    #endif /*MCU_DEV_ERROR_DETECT == STD_ON*/
    /* @implements DMCU06102 */
    #if (MCU_INIT_VALID_POINTER_REQUIRED == STD_OFF)
    Mcu_CfgPtr = &MCU_INIT_CONFIG_PC;
    #else /*MCU_INIT_VALID_POINTER_REQUIRED == STD_OFF*/
    Mcu_CfgPtr = ConfigPtr;
    #endif /*MCU_INIT_VALID_POINTER_REQUIRED == STD_OFF*/
    /* @implements DMCU06103 */
    /* polyspace +1 MISRA-C3:D4.14 [Justified:Unset] "It's chec
    Mcu_LLD_Init (Mcu_CfgPtr->McuLLD_Config);
    #if (MCU_DEV_ERROR_DETECT == STD_ON)
    #endif /* (MCU_DEV_ERROR_DETECT == STD_ON) */
}
    
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    /* @implements DMCU06103 */
    /* polyspace +1 MISRA-C3:D4.14 [Justified:Unset] "It's check
    Mcu_LLD_Init (Mcu_CfgPtr->McuLLD_Config);
    #if (MCU_DEV_ERROR_DETECT == STD_ON)
    #endif /* (MCU_DEV_ERROR_DETECT == STD_ON) */
}
    
```



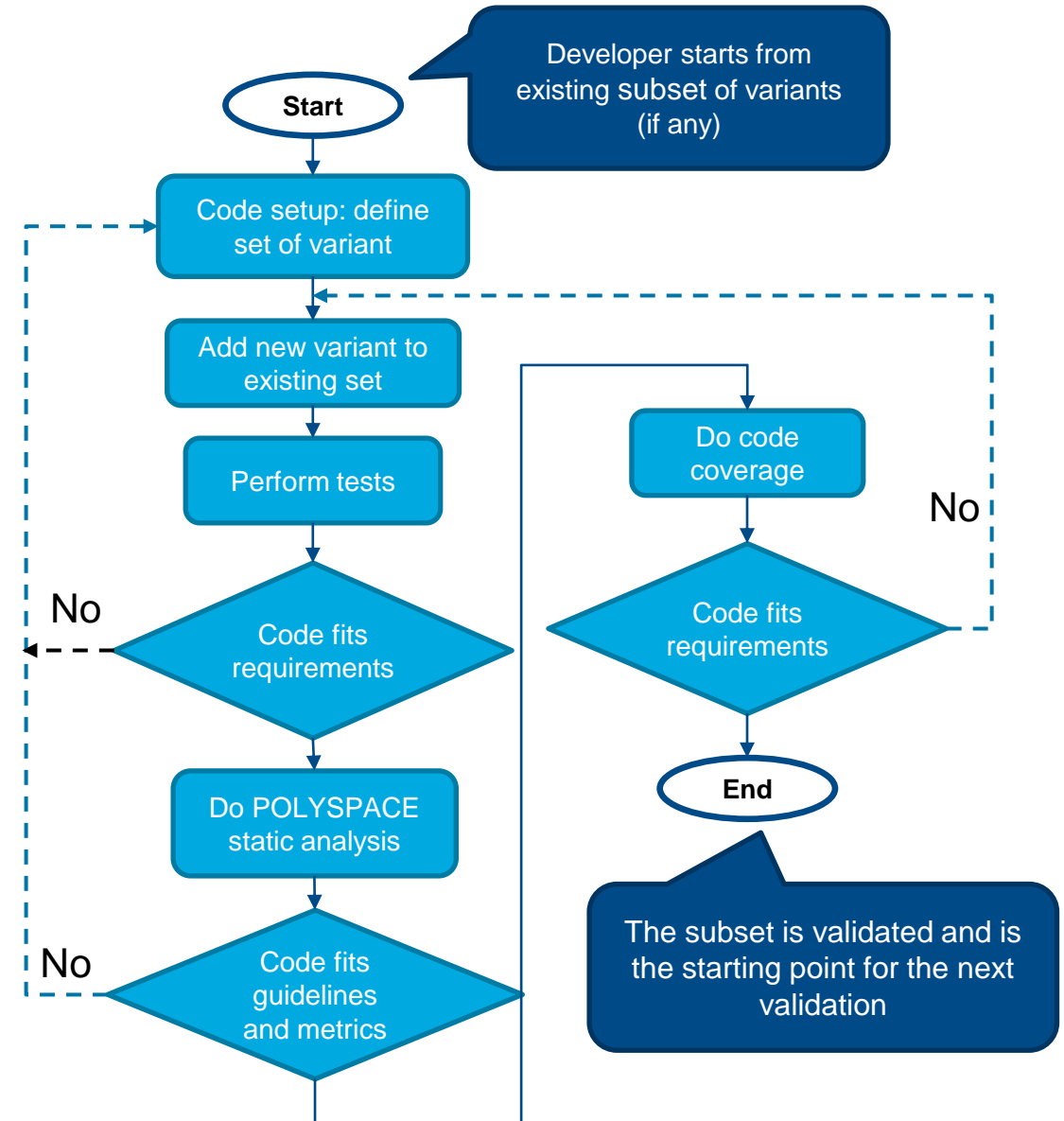
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    #endif /*MCU_INIT_VALID_POINTER_REQUIRED == STD_ON*/
    {
        /* polyspace +2 MISRA-C3:17.7 [Justified:Unset] "Det APIs return alway
        /* @implements DMCU06101 */
        Det_ReportError ( (uint16) MCU_MODULE_ID, (uint8) MCU_INSTANCE_ID, \
        (uint8) MCU_INIT_ID, (uint8) MCU_E_INIT_FAILED);
    }
    else
    {
    #endif /*MCU_DEV_ERROR_DETECT == STD_ON*/
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    /* polyspace +1 MISRA-C3:D4.14 [Justified:Unset] "It's checked when DE
    Mcu_LLD_Init (Mcu_CfgPtr->McuLLD_Config);
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    #endif /* (MCU_DEV_ERROR_DETECT == STD_ON) */
}
    
```

# Verification and Validation process

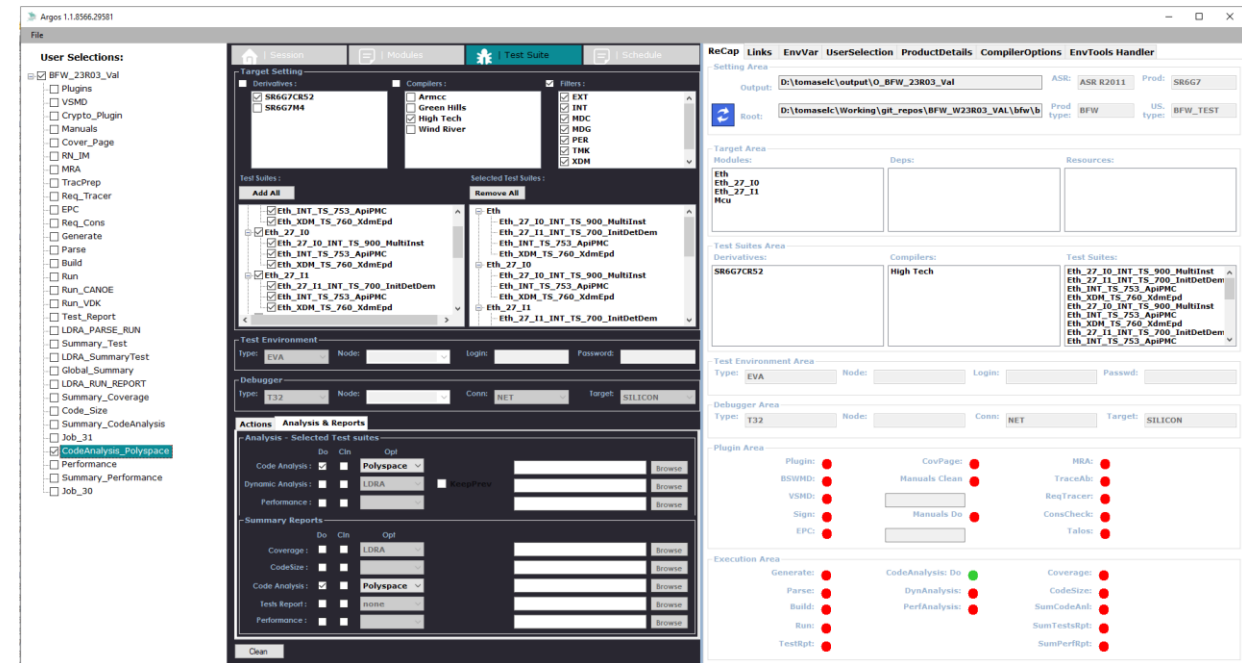
- Each SW variant is verified
  - Functional test on target
  - Code Coverage (Statements, Branch Coverage, MC/DC Coverage)
  - HIS metrics (e.g. Cyclomatic Complexity, Comment Density – using Polyspace Bug Finder)
  - Static Analysis (MISRA, Cert-C, CWE – using Polyspace Bug Finder)
  - Custom naming convention (using Polyspace Bug Finder)
  
- Consolidate results for each category





# Leverage Polyspace to analyze SW variants

- Framework (BFW) to select single variant and run VnV
  - User can select architecture/compiler/target and run one of the test mentioned in the VnV process
  - The BFW collect all user selections to invoke the testing tool
- STMicroelectronics relies on Polyspace for static code analysis
  - SW variants compliant with ISO 26262
  - Fully configurable using script
  - Supports all architectures and compilers



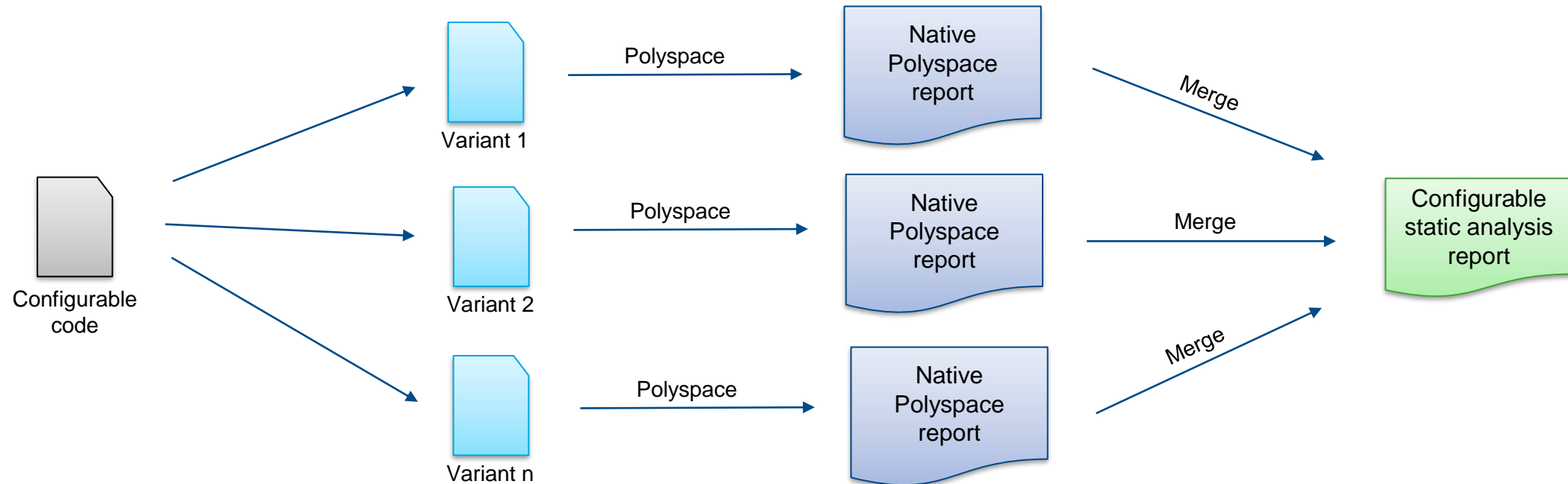
# Managing Polyspace findings

- The AUTOSAR software quality team wrote a document<sup>(1)</sup> that defines which static analysis metrics and which thresholds shall be applied to the AUTOSAR software
- Polyspace gives a severity level for defect
  - Defect with HIGH impact must be fixed in configurable code
- MISRA C:2012
  - Mandatory: the standard does not permit deviation from these rules. The violation must be solved in configurable code
  - Required/Advisory: the standard permits only the deviations that are recorded and authorized. The violation is derogated directly in code using a specific notation

<sup>(1)</sup> Static\_Analysis\_Metrics\_&\_Coding\_Guidelines

# Polyspace results of configurable software

- Polyspace can generate analysis report for each variant analyzed
- An aggregated report is generated from single variant analysis to measure code quality of the complete configurable software



## Results

- Applying this methodology, the number of variants to be verified to ensure completeness of the code analysis and the structural coverage decrease drastically

Driver	Number of Boolean preprocessor macro (#define)	Number of SW variants considering only Boolean parameters	Subset of variants	Coverage score	Compliance with Static Analysis Metric Guidelines
MCU	58	$2^{58} = 288 \cdot 10^{15}$	177	100%	100%
CAN	50	$2^{50} = 112 \cdot 10^{13}$	179	100%	100%

- Structural coverage is verified
- Thanks to Polyspace, errors in the software are found earlier, before the delivery to customer, and quality standards are fully met



## Take away

- Significant improvement of
  - productivity of ST development team
  - the quality of the configurable software
- Reusable framework beyond firmware development
  - Other teams (e.g. Safety Library team) are adopting this framework
- Possible to extend this method to other software verification activities

## Next steps

- Automatic extraction of the smallest software variants
- Improve code metrics consolidation across variants
- Extend code verification to formal code verification (e.g. Polyspace Code Prover)

Thank you!  
Any questions?