CPU, FPGA, and I/O Solutions for Real-Time Simulation and Testing

Sam Mirsky , Application Engineering, MathWorks Martin Stoller, CEO, Speedgoat



CPU, FPGA, and I/O Solutions for Real-Time Simulation and Testing



© 2017 The MathWorks, Inc. and Speedgoat GmbH



Agenda

- Introduction to Real-Time Simulation and Testing (RTST) including Rapid Control Prototyping (RCP) and Hardware-in-the-loop(HIL) simulation
- MathWorks Model-Based Design workflow from Desktop simulation to Real-Time execution
- Integration with other MathWorks products
- Speedgoat Hardware
- How MathWorks helps you to achieve your next RTST project



Why perform Real-Time Simulation and Testing?



То

- Test and investigate complex control design that is expensive to test on the field
- Reduce time to market for your engineering products
- Save costs by detecting errors early in your design process by validating your simulation model in real time with actual hardware and I/O



User Story: Gulfstream Aerospace, USA Hardware-in-the-Loop Simulation of Aircraft Engines





Gulfstream G650 business jet

Gulfstream Aerospace Corporation (GAC), located in Savannah GA, USA, produces high-end civilian business jets.

MathWorks and Speedgoat are providing a complete Hardware-in-the-Loop solution to simulate two interconnected engines, tested against the full authority digital engine controller (FADEC).





MathWorks **speedgoat**

User Story: AGCO, Germany/France/Finland Hardware-in-the-Loop Simulation of Tractors and Agricultural Machinery



"Speedgoat systems offer state of the art performance with application level support included, enabling detailed modeling of the tractor environment for ECU testing and development"

- Automated testing of controllers for tractors and other agricultural machinery using Hardware-in-the-Loop test benches
- Drivetrain and engine models
- Implement a complete testing solution
- Improving the quality of the final product





Jürgen Weinbuch, AGCO Fendt

MathWorks **speedgoat**

User Story: SuperGrid Institute, France Rapid Control Prototyping for Distributed DC-DC Converters



"The transition from design model to realtime software was very fast thanks to the complete compatibility between MATLAB & Simulink and Speedgoat."

Piotr Dworakowski, Supergrid

- Speedgoat hardware as central and distributed controllers for highly efficient and compact DC-DC power converters
- Power converter to operate at 20kHz closed-loop
- Controls algorithms implemented on CPU and FPGAs, connected to DC-DC converters with analog, fiber optic, and digital pulse train I/O
- Fast and agile development of next generation power distribution technology over extended ranges







Rapid Control Prototyping



Automatically generate code from the simulation model for real-time testing of the control algorithms



Development computer



MATLAB, Simulink, MATLAB Coder, Simulink Coder, and Simulink Real-Time



Real-time controls application autogenerated from Simulink

📣 MathWorks[,] **speedgoat**

Hardware-in-the-Loop(HIL) simulation



Automatically generate code from the simulation model for real-time system simulation of hardware for testing the real controller, FPGA, or PLC





MATLAB, Simulink, MATLAB Coder Simulink Coder, and Simulink Real-Time



Plant simulation application autogenerated from Simulink



Agenda

- Introduction to Real-Time Simulation and Testing (RTST) including Rapid Control Prototyping (RCP) and Hardware-in-the-loop(HIL) simulation
- MathWorks Model-Based Design workflow from Desktop simulation to Real-Time execution
- Integration with other MathWorks products
- Speedgoat Hardware
- How MathWorks helps you to achieve your next RTST project



Create model and build and test





How to get started and run your model in real time





Agenda

- Introduction to Real-Time Simulation and Testing (RTST) including Rapid Control Prototyping (RCP) and Hardware-in-the-loop(HIL) simulation
- MathWorks Model-Based Design workflow from Desktop simulation to Real-Time execution
- Integration with other MathWorks products
- Speedgoat Hardware
- How MathWorks helps you to achieve your next RTST project



Integrated solution

- Test automation
- Running models on FPGAs
- Automate analysis/optimizations
- Physical modeling, Powertrain blockset

One workflow with software and hardware used for Real-Time Simulation and Testing



Automated Testing with Simulink Test

Real-Time Test Automation, ideal for Hardware-in-the-Loop



Target Computer

Physical System

- 0

Description

MathWorks **speedgoat**

Fully Tested Algorithm in Simulink Test



MathWorks[•] **speedgoat**

Running models on Simulink programmable FPGA I/O modules





HDL Workflow Advisor - speedgoat_RTTM/FPGA_algorithm								×
ile Edit Run Help								
Find: 🔍 🔶 🛱								
 HDL Workflow Advisor 1. Set Target ^1.1. Set Target Device ^1.2. Set Target Refer ^1.3. Set Target Interf 1.4. Set Target Frequee 2. Prepare Model For HDL 0 2.1. Check Global Setti ^2.2. Check Algebraic ^2.3. Check Block Con ^2.4. Check Sample Ti 3.1. Set Code Generation 3.1. Set Code Generation 3.1. Set Code Generation 4. Embedded System Integ 4.1. Create Project 4.2. Build FPGA Bitstree 5.1. Generate Simulink 	e and Synthesis Tool ence Design face ncy Code Generation ngs Loops npatibility imes on Options ode and IP Core gration am : Real-Time interface	.1. Set Target Device ar Analysis (^Triggers Up Set Target Device and Input Parameters Target workflow: S Target platform: S Synthesis tool: S Family: KintexU Package: S Project folder: S Run This Task Result: Not Run Click Run This Task	Ad Synthesis Tool pdate Diagram) Synthesis Tool for HDL of imulink Real-Time FPGA peedgoat IO342-1450k noose a platform peedgoat IO321 peedgoat IO331-6 peedgoat IO333-325K peedgoat IO333-410k peedgoat IO333-410k peedgoat IO342-1450k C.	code generation		Launch Board	I Manager Refresh Browse	▼ ▼

MathWorks[®] **speedgoat**

Physical modeling for HIL simulation

- Simscape
- Simscape Driveline
- Simscape Electronics
- Simscape Multibody
- Simscape Power Systems
- Simscape Fluids
- Powertrain blockset in Auto

Libraries to utilize for HIL simulation





Agenda

- Introduction to Real-Time Simulation and Testing (RTST) including Rapid Control Prototyping (RCP) and Hardware-in-the-loop(HIL) simulation
- MathWorks Model-Based Design workflow from Desktop simulation to Real-Time execution
- Integration with other MathWorks products
- Speedgoat Hardware
- How MathWorks helps you to achieve your next RTST project



Made for Simulink, Tailored to Your Needs



- Seamless workflow experience: Speedgoat and Simulink Real-Time are expressly designed to work together
- Turnkey configured to your needs:
 - sample rate
 - I/O and protocols
 - environmental
- Highest performance, vast range of I/O, scalable at any time
- Continuously prove and improve your next generation controls, DSP, vision, and plan designs with hardware



Mainstay Real-Time Target Machines and HIL simulators



Full size hardware-in-the-loop simulators, and desktop prototyping and HIL units

- Performance real-time target machine with Core i7 and Xeon CPUs and rack solutions
- Baseline real-time target machine

Rugged controls, DSP, and vision prototyping units for mobile and in-vehicle use

- Mobile real-time target machine
- Baseline real-time target machine



Vast range of over 200 I/O Modules





Analog	
A/D D/A 16-24	bit







Communications CAN, UDP, PROFINET...



Digital TTL, RS422, LVDS

Relays



Encoders Resolvers



Shared Memory 2.5 Gbps



Resistors High Precision



Fault Injection

SPST, SPDT, DPST



Temperature Strain

Included in delivery

- I/O module installed into Real-time target machine
- Simulink driver blocks and test models included
- Cable and terminal board
- Optional panels and boxes



Timing GPS, IRIG, PTP



Video Camera Link, USB

MathWorks **speedgoat**

Speedgoat Products and Services

I/O Connectivity Examples



Analog	A/D, D/A, simultaneous, low latency, high resolution, frame support, up to 5GHz
Digital	TTL, LVCMOS, LVDS, RS422, RS485, 24V, 48V,
Pulse Train	PWM generation and capture, interrupt, negation
Encoders	Absolute and incremental encoder measurement and simulation (quadrature and SSI), EnDAT 2.2, SSI2, SPI, and BiSS encoder measurement
Shared Memory	Shared and reflective memory
Fault Insertion	Electromechanical or solid state switches for fault insertion
Temperature	Thermocouple, RTD, and NTC measurement and simulation
Strain, Pressure	Strain gauges and pressure sensor measurement and simulation
Accelerometers	IEPE/ICP measurement
Resistors	Resistor, potentiometer, and reed-relay (SPDT, DPST, SPST) simulation

. . .



Protocols Examples



Multi-Industry

- Serial RS232, RS422, RS485
- Real-time UDP CAN / SAE J1939
- SPI Master and Slave
- I2C Master and Slave
- Shared/reflective memory
- IRIG with GPS
- Precision Time Protocol (PTP) 1588

Vision

- USB 3 UVC Vision
- GigE Vision
- CameraLink
- HDMI and SDI
- MIPI CSI-2



Industrial Automation

- Profinet
- Modbus/TCP
- Modbus RTU
- Profibus
- EtherCAT
- EtherNet/IP
- POWERLINK

IIOT and Robotics

- DDS
- OPC UA
- MQTT
- TSN
- ...



Automotive

- XCP Master/Slave (CANape/INCA)
- CAN / SAE J1939
- LIN 2.1
- SENT
- FlexRay
- Cam and Crank
- Resolver measurement and emulation
- ...



Aerospace

- ARINC 429
- ARINC 629
- ARINC 664P7/AFDX
- MIL-STD-1553
- Synchro, Resolver
- RVDT, LVDT
- SDLC, HDLC
- ...







Examples for Hardware-in-the-Loop

Analog and digital

- Large portfolio of I/O modules available
- High-density connectors and high channel count
- Terminal boards and breakout panels

Encoder emulation

- Absolute / Incremental, hall sensors
- EnDat, BiSS
- Synchro/Resolver, LVDT/RVDT
- Cam / Crank

Emulation of passive components

- High precision resistors (thermocouples / RTD)
- Potentiometer
- Reed relays
- Strain gauges, pressure sensors

Fault insertion

- Wide range of channel counts and fault bus configurations
- Designed for safety critical applications

Battery simulation

Many Node with Protocols Simulators





Examples of rack scale HIL simulators



Example of a 128 protocol node simulator

Profinet, EtherNet/IP, EtherCAT, Modbus, Powerlink, and more, plus a wide range of analog and digital I/O, to simulate complete ships, smart grids, wind farms, or train networks. 100+ interconnected units with thousands of nodes are feasible

Simulink Programmable FPGA I/O modules

- Xilinx Artix, Kintex and Ultrascale, and Intel FPGAs
- With support for analog, digital (DIO, PWM, encoders, SPI, I2C, cam/crank, UART,) and vision I/O
- Very scalable: Many FPGA I/O modules can be interconnected with lowest latency links. Over 50
 interconnected FPGAs with hundreds of I/O links are not a problem.
- Allows to achieve fastest closed-loop rates e.g. for motor and inverter controls, and fastest processing and data logging e.g. for high speed analog and digital vision processing applications









Fast-Track to Real-Time: Add Driver Blocks and Connect with Your Hardware





- 1. Drag, drop, and connect Speedgoat Simulink driver blocks to your model
- 2. Configure I/O settings in dialog fields
- 3. Connect your target computer with your hardware under test

Seamless Simulink Workflow

Automatically build, connect, and run real-time applications with your hardware



"The transition from model design to real-time was very fast thanks to the complete compatibility between MATLAB, Simulink, and Speedgoat solutions" *Piotr Dworakowski, DC/DC Power Converters team lead, Supergrid, France*

Seamless Simulink Workflow

Rapidly Prove your Designs and Try new Ideas, all from within Simulink

- Monitor and tune signal parameters with Simulink HMI blocks on the fly in real-time
- Live stream, monitor, and log signal data to Simulink Simulation Data Inspector, compare with desktop simulation results, and feedback results to your design



"The target machine works flawlessly with Simulink, providing me with powerful tools for prototyping and debugging."

Jonathan Abir, School of Aerospace, Cranfield University, UK



How MathWorks and Speedgoat can help you build your Real-Time Simulation and Testing project ?

- Technical support
- Training
- Consulting services

Contact us by going to our website



https://www.mathworks.com/products/simulink-real-time.html https://www.speedgoat.com/